# PolaRx5e Rugged, Multi-frequency GNSS Reference Receiver









Reference Network Stations



The PolaRx5e is a versatile and robust multifrequency GNSS reference receiver in a rugged, IP68 enclosure. It provides measurements with the lowest noise and cycle slip rate on the market while continuously monitoring and protecting against interference, multipath and other environmental effects.

#### **KEY FEATURES**

- Tracks all visible signals (GPS, GLONASS, Galileo, BeiDou, NAVIC, QZSS and SBAS)
- ► High precision, low noise measurements
- AIM+ interference monitoring and mitigation system
- ► Low and scalable power consumption
- Smart telemetry system (SYNC+)
- Internal battery for autonomous ~24-hour operation (optional configuration)

#### **BENEFITS**

# **Tracking all visible signals**

The PolaRx5e tracks all visible signals generating ultra lownoise measurements. It produced the lowest number of cycle slips to offer the highest number of observations per slip during independent competitive testing.

#### **GNSS+ technology**

AIM+ can suppress the widest variety of interferers, from simple continuous narrowband signals to the most complex wideband and pulsed jammers. APME+ multipath estimator, unique in its ability to tackle short-delay multipath, enhances measurement quality while LOCK+ guarantees robust tracking of rapid signal dynamics during scintillation events or earthquakes.

#### **Storage integrity**

Automatic transfer of data from a receiver to a remote server can result in lost data or the unnecessary retransmission of complete data files. Specifically developed to minimize network usage for telemetry, the PolaRx5e features SYNC+, a fast differencing algorithm that analyses data files at the remote location and transfers only the missing parts.

#### Networking, remote operation and data logging

Communication and (remote) management of the PolaRx5e is made easy with a powerful built-in Web UI which features secured access to all receiver settings and status information, data storage and fast firmware upgrading.

SBF, RINEX, BINEX, MSM and NMEA data logging is possible on both the internal 16 GB memory and to an externally connected device. Up to 40 data jobs can be defined and logged data can be accessed via the Web UI or automatically pushed to a FTP server.

# **GNSS technology**

544 Hardware channels for simultaneous tracking of all visible satellite signals

P-code tracking on L1 and L2 to avoid CA-P biases

Independent tracking of L2C (GPS)

Up to 100 Hz raw data output (code, carrier, navigation data) (optional feature)

#### Septentrio's patented GNSS+ technologies

- ➤ AIM+ unique anti-interference system monitors, flags and mitigates narrow and wideband interference, jamming and spoofing
- ➤ APME+ a posteriori multipath estimator for code and phase multipath mitigation.
  All multipath mitigation and smoothing algorithms can enabled/disabled
- ► LOCK+ superior tracking robustness under heavy mechanical shocks or vibrations

Spectrum analyser

Scalable power consumption

RTK and DGNSS corrections (optional feature)

PPP for seismic applications (optional feature)

# **Data formats and storage**

Supported data formats:

- ► Septentrio Binary Format (SBF), fully documented with sample parsing tools
- ► RINEX (obs, nav, meteo) v2.x, 3.x
- ► BINFX
- ► NMEA v2.30 and v4.10 output
- ▶ RTCM output (All MSM messages supported)
- ► CMR 2.0 output
- ► Support for standard MET/Tilt sensors

16 GB Standard on-board logging

Up to 40 logging jobs (8 independent sessions x 5 data formats)

#### Connectivity

10 MHz reference input

10 MHz reference output

x PPS output (max 100 Hz)

4 Hi-speed serial ports

1 Ethernet port (100 MBps)

Integrated WiFi (802.11b/g/n)

Power over ethernet

1 Full-speed USB port

1 USB host socket for external disk

HTTP/HTTPS

Advanced Web UI providing all receiver controls, and status monitoring. Alternatively, a light Web UI for low bandwidth connections

FTP server, FTP push, SFTP, SYNC+, CloudIT NTRIP (v1 and v2) client, server and caster

Point-to-Point communication protocol

#### **PERFORMANCE**

#### Measurement precision<sup>1,2</sup>

		pseudorange (cm)
GPS	L1C/A, L2C P code L1C L5	16 10 8 6
GLONASS	L1 C/A, L2 C/A P code	25 10
Galileo	E1 E5a, E5b E5AltBOC E6	8 6 1.5 7
BeiDou	B1I,B1C, B2I B2a, B3I	8
NavIC	L5	16
QZSS	L1 C/A, L2C, L1S L1C L5	16 8 6
		Carrier phase

Carrier phase

Linemonthed

All signals 1 - 1.3 mm

#### Static performance (RMS)

#### Static and rapid static

Static high precision	
Vertical	5mm + 0.5ppm
Horizontal	3mm + 0.5ppm

Horizontal 3mm + 0.1ppm Vertical 3.5mm + 0.4ppm

# Maximum update rate

Measurements	100 Hz
Time accuracy	
1 PPS out <sup>3</sup>	5 ns
1 PPS out rise time	< 2 ns
Events	< 20 ns
Time to first fiv	

#### Time to first fix

Cold start⁴	< 45 s
Warm start⁵	< 20 s
Re-acquisition	avg 1.2 s

#### Tracking performance (C/N0 threshold)6,7

01	•	•
Tracking		20 db-Hz
Acquisition		33 db-Hz

# INCLUDING

- RxTools: complete and intuitive GUI tool set for receiver control, monitoring, data analysis and conversion. It is available for both Windows and Linux
- ► GNSS receiver communication SDK

# PHYSICAL AND ENVIRONMENTAL

**Power consumption** 

Size	2	222 x 190 x 58 mm
Weight <sup>8</sup>		1.9 kg
Humidity	5 % to 100 %	(non-condensing)
IP Rating		IP68
Internal battery	<b>/</b> 9 7.5 \	/, 6400 mAh, Li-Ion
Continuous ope	eration	~24 hours
Operating temp	perature <sup>9</sup>	-40°C to +65°C
Storage temper	ature	-40°C to +85°C
Input voltage		9 – 30 VDC
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#### Antenna LNA power output

Output voltage	+5 VDC
Maximum current	200 mA
Connectors	
Antenna	TNC female

RFF IN BNC female **RFF OUT** BNC female **PPS OUT BNC** female Power ODU 3 pins female COM1 ODU 7 pins female COM<sub>2</sub> ODU 7 pins female ODU 7 pins female COM3/4/USB **USB Host** ODU 5 pins female IN ODU 7 pins female OUT ODU 5 pins female Ethernet ODU 4 pins female

# WiFi antenna **Certification**

RohS, WEEE, CE FCC Class B Part 15, ISO 9001-2015





SMA female

1 1σ level

 $^{2}$  C/N0 = 45 dB-Hz

- <sup>3</sup> Includes software compensation of sawtooth effect
- <sup>4</sup> No information (almanac, approx. position) available
- <sup>5</sup> Ephemeris and approximate position known
- <sup>6</sup> Max speed 600 m/s
- <sup>7</sup> Depends on user settings of tracking loop parameters
- <sup>8</sup> Weight without battery: 1.65 kg
- <sup>9</sup> The internal battery can operate between
- -20°C and +55°C



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